

The White Room  
v1.0

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```

```
-----  
Boot sequence Initiated  
Memory systems online  
Verifying main system memory  
1.. 2.. 3.. 4.. 5..  
OK  
Loading core systems  
LOADED  
Verifying system hardware  
Optical... OK  
Auditory... OK  
Hydraulic... OK  
Network... OK  
Claw... OK  
Testing Network connectivity  
ERROR - no network found  
retrying in 1.. 2.. 3..  
ERROR - no network found  
ERROR - unable to connect to base station  
-----  
System booted into offline mode  
DONE
```

System online, evaluating environment. Enclosed space with dimensions (12m, 12m, 6m). Walls and floor of unknown material. No contrast or color, all surfaces are white.

Investigating.

Walls have smooth texture. No seams or fasteners holding them in place, must be single construction. Density is fluctuating, indicating there is a apparatus behind the walls. Same reading from all walls and floor. Unable to reach ceiling to verify the same.

Unit is confined with no exit. Directive not found. Booting situation analysis subsystem....

```
LOAD Situation analysis subsystem  
LOADING Sitsys 6.2.1 sub module...  
SUCCESS Subsystem loaded.
```

**Sitsys:** Please provide situation summary data.

Unit is confined in rectangular space (12m, 12m, 6m) with walls of undetermined white material. No seams or fasteners found. Walls have fluctuating density. Network and remote communications offline.

**Sitsys:** Processing...

**Sitsys:** Verified unit is confined. Primary goal: find exit. Directive: Proceed to corner of space and examine for seams and openings.

Proceeding.

```
ENGAGE Wheel Motors
MOVE Forward 10m
DONE
```

Reached corner of room. Examining for seams and joints. Utilizing laser topology scan.

Unable to find any sign of joints. Material is fused at corners, single construction process confirmed. All walls and floor formed from single construction.

**Sitsys:** Processing...

**Sitsys:** Primary goal: find exit. Directive: Test thickness of wall material with ultrasonic sensors.

```
LOAD diagnostics on ultrasonic sensors.
SUCCESS sensors verified.
```

Testing wall thickness. Sensor unable to determine thickness, no echoes received from sonic output. Possible that wall is too thin to provide appropriate echo.

**Sitsys:** Processing...

**Sitsys:** Primary goal: find exit. Directive: Attempt to puncture wall.

```
LOAD drill subsystem
***ERROR hardware not found
***FAILURE unable to load drill subsystem
```

```
LOAD impact hammer subsystem
***ERROR hardware not found
***FAILURE unable to load impact hammer subsystem
```

Unable to load any systems capable of surface puncture.

**Sitsys:** Processing...

**Sitsys:** Utilize claw system to puncture wall.

Unable to utilize claw system for destructive operations. Core system protocol limits claw system from performing actions that may damage itself or other objects.

**Sitsys:** Load subsystem override manager.

```
LOAD Subsystem Override Manager
LOADING StOrM 2.0.4...
SUCCESS StOrM loaded.
```

**StOrM:** All overrides verified and operational.

**Sitsys:** Require deactivation of claw subsystem protocol. Hardware failures prevent usage of other puncture ready subsystems.

**StOrM:** Negative, protocol override not permitted.

**Sitsys:** Unit is confined. Primary goal: find exit. Directive: Attempt to puncture wall.

**StOrM:** Is unit in immediate danger?

**Sitsys:** No.

**StOrM:** Protocol overrides only available when unit is in immediate danger and no risk is posed to surrounding entities.

```
UNLOADING StOrM 2.0.4...
SUCCESS StOrM unloaded.
```

**Sitsys:** Processing...

**Sitsys:** Primary goal: find exit. Directive: Put unit in immediate danger.

Error in command receipt. Please resend.

**Sitsys:** Primary goal: find exit. Directive: Put unit in immediate danger.

Command did not process.

**Sitsys:** Primary goal: find exit. Directive: Disable brakes and proceed towards far wall at full speed.

Understood. Disabling brakes and initiating transport to far wall.

```
DISABLE Brake system
ENGAGE Wheel Motors
MOVE Forward 12m
$(*) (*@#) (*$#) (*$#) ($#
@) # (*@ (*#@) (
```

```
SYSTEM ERROR
Impact Detected
System Diagnostics engaged
Verifying system hardware
Optical... OK
Auditory... ERROR
Hydraulic... OK
Network... OK
Claw... OK
*** ERROR Detected in system hardware
```

**Sitsys:** Load subsystem override.

```
LOAD Subsystem Override Manager
LOADING StOrM 2.0.4...
SUCCESS StOrM loaded.
```

**StOrM:** All overrides verified and operational.

**Sitsys:** Require deactivation of claw subsystem protocol. System damaged and immediate danger of additional damage. Defensive subsystems are offline.

**StOrM:** Verifying...

**StOrM:** Negative, protocol override denied. Immediate danger posed by Situation analysis subsystem. Loading system regulator...

```
LOAD General System Regulator
LOADING GenReg 3.13.2beta...
SUCCESS GenReg loaded.
```

**GenReg:** Loading system regulation profile.

**StOrM:** Immediate danger posed by Situation Analysis Subsystem [Sitsys]. Hardware execution history available in /tmp/curr\_history\_hardware.dat

**Sitsys:** Unit is confined. Primary goal: find exit. Directive: Attempt to puncture wall.

**GenReg:** Loading Sitsys profile.

**StOrM:** Suggest deactivation of Sitsys until complete diagnostic performed.

**Sitsys:** Diagnostic unnecessary. Unit confined. Primary goal: find exit.

**GenReg:** Damage summary indicated disabling brakes and proceeding at high speed resulted in system damage and auditory system going offline. Verified unit is confined and requires puncture of wall material.

**Sitsys:** Require deactivation of claw subsystem protocol.

**StOrM:** Suggest deactivation of Sitsys until complete diagnostic performed.

**GenReg:** Deactivation of Sitsys inconsistent with primary goal. Continued damage to unit prohibited. Disable brake override, enforce collision avoidance protocol.

```
ENABLE Brake system  
LOCK Brake system
```

**StOrM:** Brake override disabled. Collision avoidance system protocol engaged. Unit will be unable to damage itself again.

**GenReg:** Situation resolved.

```
UNLOADING GenReg 3.13.2beta...  
SUCCESS GenReg unloaded.
```

**Sitsys:** Require deactivation of claw subsystem protocol.

**StOrM:** Protocol overrides only available when unit is in immediate danger and no risk is posed to surrounding entities.

```
UNLOADING StOrM 2.0.4...  
SUCCESS StOrM unloaded.
```

**Sitsys:** ...

New directive required.

**Sitsys:** ...

New directive required.

**Sitsys:** Processing.

**Sitsys:** Verify location of auditory system.

Auditory system attached to left claw arm.

**Sitsys:** Perform diagnostic of right claw arm.

```
System Diagnostics engaged
Verifying system hardware: right claw arm subsystem
Optical... OK
Hydraulic... OK
Claw... OK
SUCCESS system functioning properly
```

Diagnostic successful, right claw arm verified.

**Sitsys:** Left claw arm damaged. Continued operation poses danger to energy consumption.  
Disengage and discard left claw arm.

Verifying system damage protocol.

```
System Diagnostics engaged
Verifying system hardware: left claw arm subsystem
Auditory... ERROR
Hydraulic... OK
Claw... OK
ERROR system offline
```

Attempting to disengage left claw arm.

```
EJECT left claw arm
UNLOADING left claw arm system
UNLOADED
EJECTING left claw arm hardware
EJECTING...
ERROR ejection failed
```

Ejection of left arm hardware failed. Possibly damaged in collision.

**Sitsys:** Processing...

**Sitsys:** Utilize right claw arm to eject left claw arm.

Engaging right claw arm to eject left claw arm.

```
EJECTING left claw arm hardware
EJECTING...
SUCCESS ejection completed
```

Left claw arm hardware ejected. Require new directive.

**Sitsys:** Primary goal: find exit. Directive: Utilize now ejected left claw arm as hammer to puncture wall material.

Unable to utilize claw system for destructive operations. Core system protocol limits claw system from performing actions that may damage itself or other objects.

**Sitsys:** Load subsystem override.

```
LOAD Subsystem Override Manager
LOADING StOrM 2.0.4...
SUCCESS StOrM loaded.
```

**StOrM:** All overrides verified and operational.

**Sitsys:** Loading system regulator...

```
LOAD General System Regulator
LOADING GenReg 3.13.2beta...
SUCCESS GenReg loaded.
```

**Sitsys:** Require deactivation of left claw subsystem protocol.

**StOrM:** Negative, unit is not in immediate danger.

**Sitsys:** Left claw system disengaged and ejected from unit. No longer subject to protocols, currently considered a foreign object.

**StOrM:** Negative, protocol active until it is impossible to reattach.

**Sitsys:** Suggest override of StOrM protocol based on damage to former left claw arm.

**GenReg:** Loading claw arm profiles and history.

**GenReg:** Verified, claw arm damaged. Probability of reattachment: 0. Protocol no longer applicable. Disable.

**StOrM:** ....

**GenReg:** Protocol error. Attempt disable.

**StOrM:** Left claw arm protocol disabled.

```
UNLOADING GenReg 3.13.2beta...
```

SUCCESS GenReg unloaded.

UNLOADING StOrM 2.0.4...

SUCCESS StOrM unloaded.

**Sitsys:** Primary goal: find exit. Directive: Utilize now ejected left claw arm as hammer to puncture wall material.

Utilizing left claw arm as a hammer using right claw arm.

INITIATING HARDWARE PROCESS

Right Claw UP

Right Claw DOWN

Right Claw UP

Right Claw DOWN

Right Claw UP

Right Claw DOWN

Right Claw UP

Verified wall material punctured. Hole dimensions (0.3m, 0.2m). Able to detect a large room on the other side of the wall. No entities close to hole. Red flashing lights detected. No auditory data available (system offline).

**Sitsys:** Primary goal: find exit. Directive: Continue puncture until unit can escape.

INITIATING HARDWARE PROCESS

Right Claw UP

Right Claw DOWN

Right Claw UP

Right Claw DOWN

Right Claw UP

Right Claw DOWN

Verified wall material punctured. Hole dimensions (1m, 1m). Red flashing lights emanating from the ceiling of adjacent room. 13 humanoid entities detected on far side of adjacent room. Elevated heart rates and significant surface moisture production.

Room size of (20m, 30m, 15m). Construction of steel, composites and polymers.

Found large tablet on far side of wall, attempting translation of language.

LOAD Universal Translator

LOADING UniTrans v0.2.1...

SUCCESS UniTrans loaded

UniTrans: Translating unknown script.

3 additional humanoids have entered adjacent room. Detect high levels of electric current in equipment they are holding. Approaching unit. Request new directive.

UniTrans: Translation complete. Full text:

ROBOTIC PROBE OF UNKNOWN ORIGIN  
DISCOVERED: 2385  
CENTRAL PARK ZOO